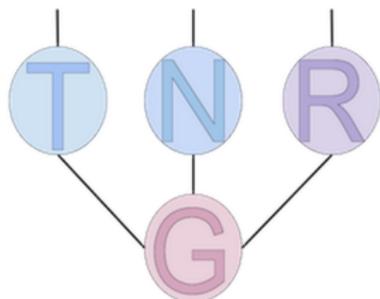


AI and TN - a love affair

Bram Vanhecke

University of Vienna

28 Nov 2023



Collaborators



Overview

¹<https://arxiv.org/abs/2208.08713>

²<https://arxiv.org/abs/2311.11894>

Overview

- Using MPS for active inference planning¹
 - What is Active inference
 - How MPS can help

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- Using MPS for active inference planning¹
 - What is Active inference
 - How MPS can help
- AD for PEPS optimization²
 - What is PEPS
 - How AD can help

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Active Inference

(solutions to) Belief updating

Action selection (and Bayesian model averaging)

$$u_t = \min_u \mathbf{o}_{t+1} \cdot \varepsilon_{t+1}^u$$

$$\varepsilon_{t+1}^u = \ln \mathbf{A} \mathbf{s}_{t+1} - \ln \mathbf{A} \mathbf{B}(u) \mathbf{s}_t$$

$$\mathbf{s}_t = \sum_{\pi} \pi_{\pi} \cdot \mathbf{s}_t^{\pi}$$

State estimation (planning as inference)

$$\mathbf{s}_t^{\pi} = \sigma(\tilde{\mathbf{A}} \cdot \mathbf{o}_t + \tilde{\mathbf{B}}_{t-1}^{\pi} \cdot \mathbf{s}_{t-1}^{\pi} + \tilde{\mathbf{B}}_t^{\pi} \cdot \mathbf{s}_{t+1}^{\pi})$$

State estimation (habitual)

$$\mathbf{s}_t^{\pi} = \sigma(\tilde{\mathbf{A}} \cdot \mathbf{o}_t + \tilde{\mathbf{C}} \mathbf{s}_{t-1}^0 + \tilde{\mathbf{C}} \cdot \mathbf{s}_{t+1}^0)$$

Policy selection

$$\pi = \sigma(\tilde{\mathbf{E}} - \mathbf{F} - \gamma \cdot \mathbf{G})$$

$$F(\pi, \tau) = \mathbf{s}_t^{\pi} \cdot (\tilde{\mathbf{s}}_t^{\pi} - \tilde{\mathbf{A}} \cdot \mathbf{o}_t - \tilde{\mathbf{B}}_{t-1}^{\pi} \cdot \mathbf{s}_{t-1}^{\pi})$$

$$G(\pi, \tau) = \mathbf{o}_t^{\pi} \cdot (\tilde{\mathbf{o}}_t^{\pi} - \mathbf{U}_t) + \mathbf{s}_t^{\pi} \cdot \mathbf{H}$$

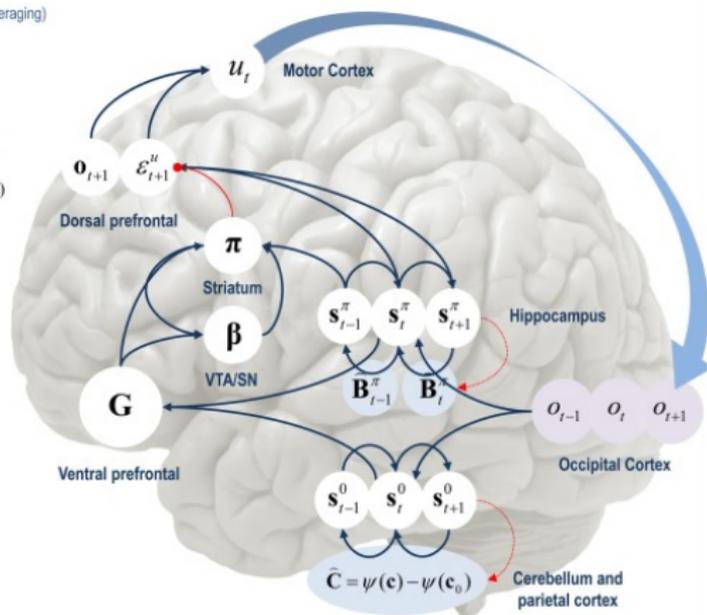
Precision (incentive salience)

$$\beta = \beta + (\pi - \pi_0) \cdot \mathbf{G}$$

Learning

$$\mathbf{c} = \mathbf{c} + \sum_{\pi} \mathbf{s}_t^{\pi} \otimes \mathbf{s}_{t-1}^{\pi}$$

Functional anatomy



Active Inference

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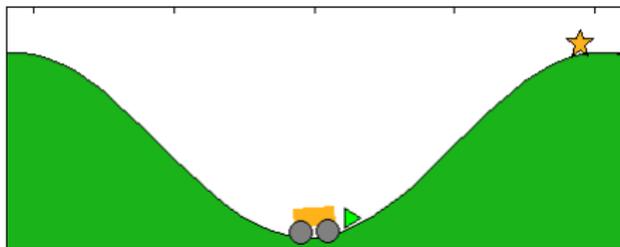
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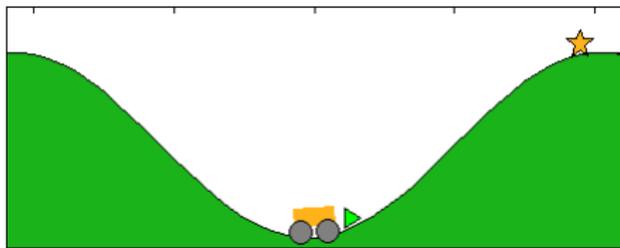
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 - the model may also be represented by a TN

Active Inference - Example - Mountain Car

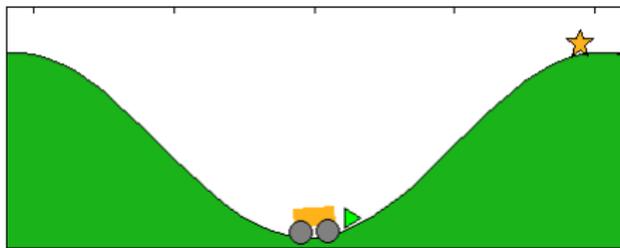


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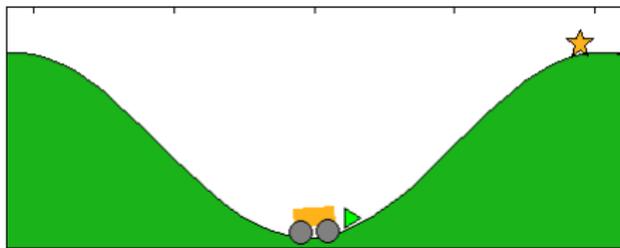
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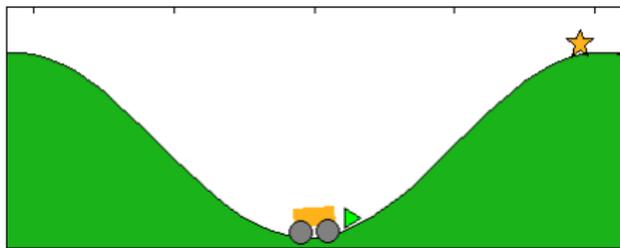
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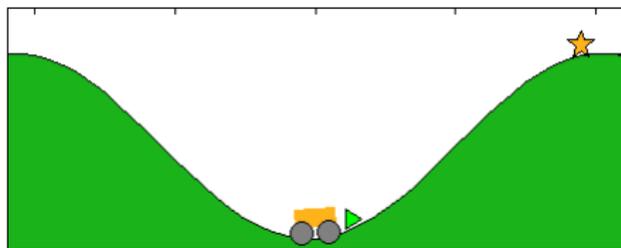
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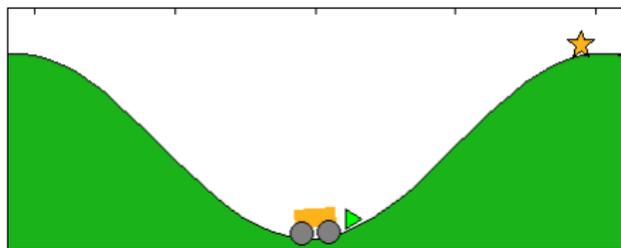
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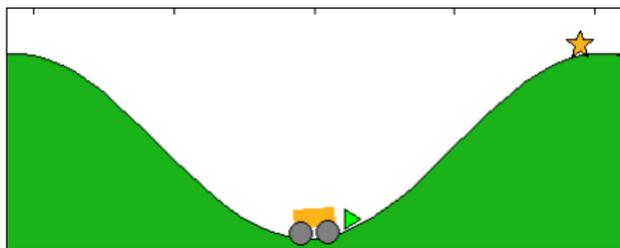
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⇒ the preferred distribution $P(o)$ is centered around the star.

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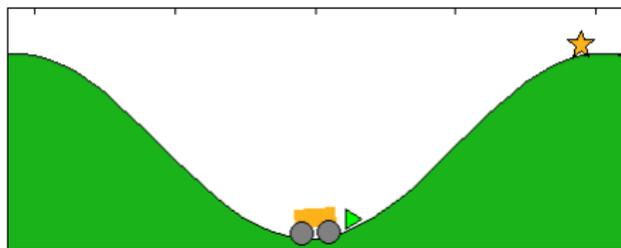
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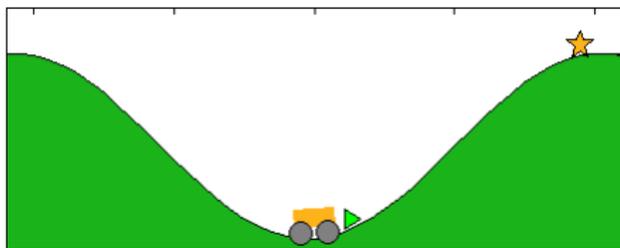
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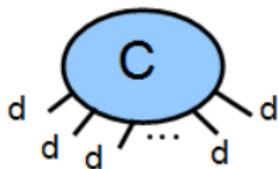
TN preliminaries

Big tensor C_{i_1, \dots, i_N}

Arbitrary tensor

($|i_k\rangle$ – local \mathcal{H} space of dim d):

$$|\Psi\rangle = \sum_{i_1, \dots, i_N} C_{i_1, i_2, \dots, i_N} |i_1 i_2 \dots i_N\rangle$$



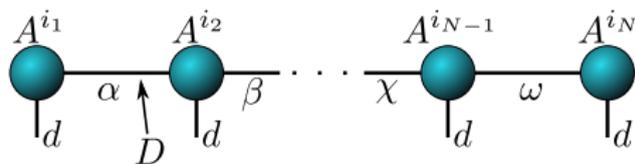
d^N parameters C_{i_1, \dots, i_N}

$\exp(N)$

Network of tensors

Matrix product state:

$$\sum_{i_1, \dots, i_N} \sum_{\{\alpha\beta\dots\omega\}} A_{\alpha}^{i_1} A_{\alpha\beta}^{i_2} \dots A_{\chi\omega}^{i_{N-1}} A_{\omega}^{i_N} |i_1 i_2 \dots i_N\rangle$$

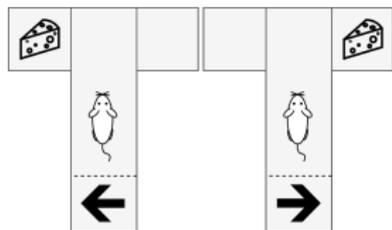


$\mathcal{O}(ND^2d)$ par. (D – dim of bond index)

$\text{poly}(N)$

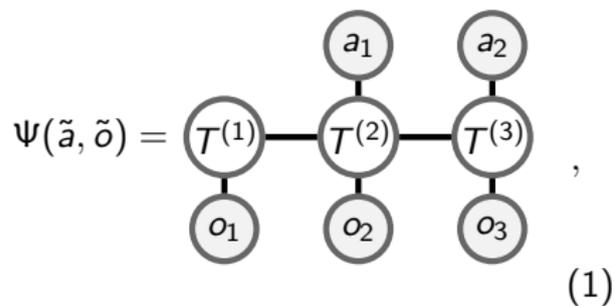
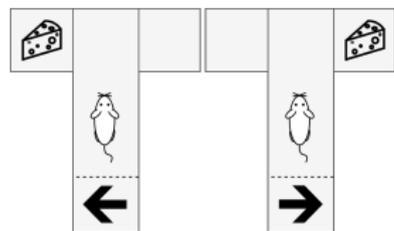
T-maze

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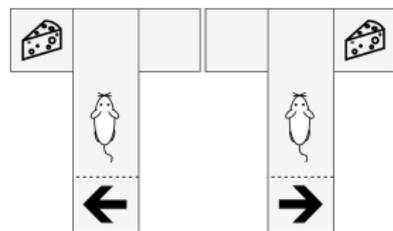
$$\Psi(\tilde{a}, \tilde{o}) = \begin{array}{c} \begin{array}{ccc} & a_1 & a_2 \\ & | & | \\ T^{(1)} & - T^{(2)} & - T^{(3)} \\ & | & | \\ o_1 & o_2 & o_3 \end{array} \end{array}, \quad (1)$$

T-maze



- Generate data set of consistent actions and observations

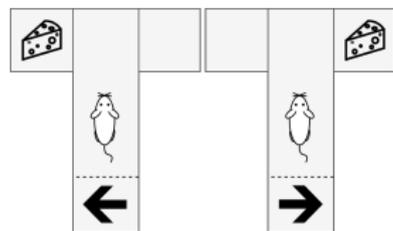
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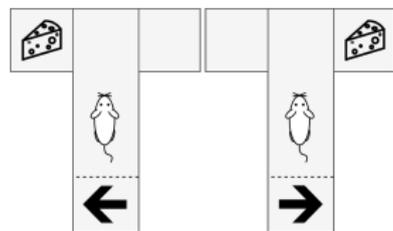
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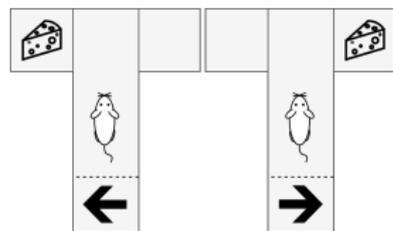
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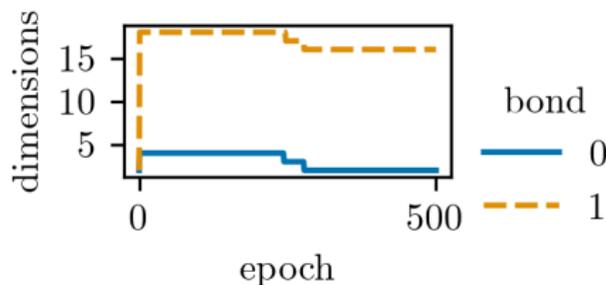
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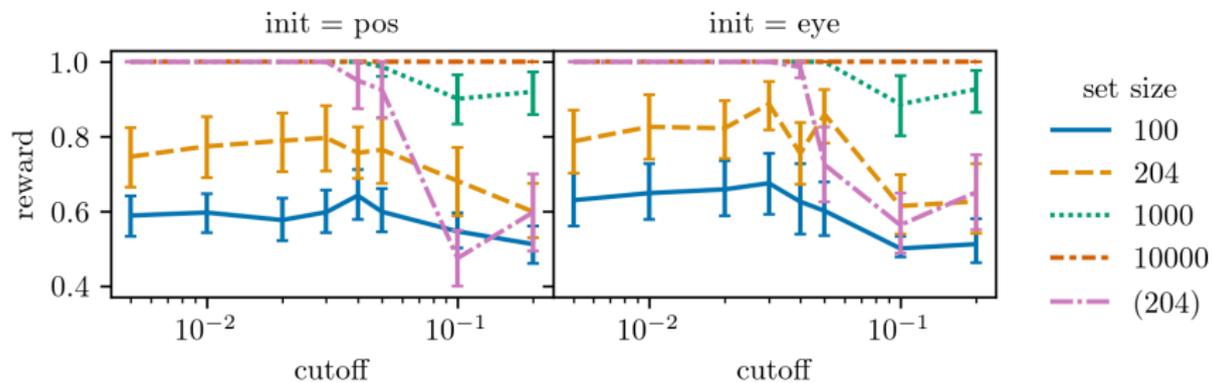
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T-maze - Results

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Outlook

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- More complicated models

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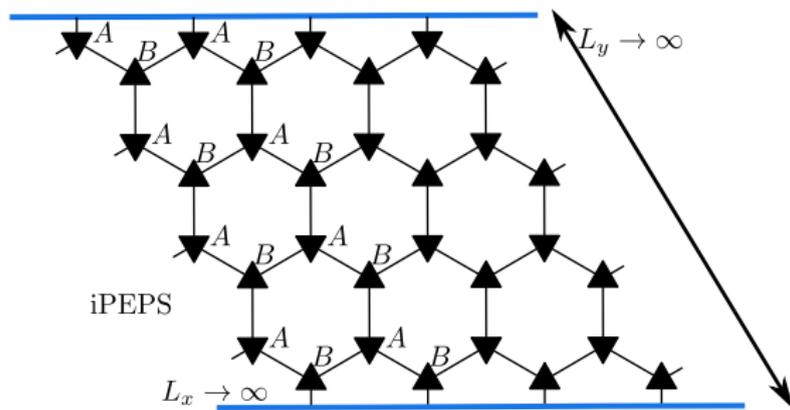
- More complicated models
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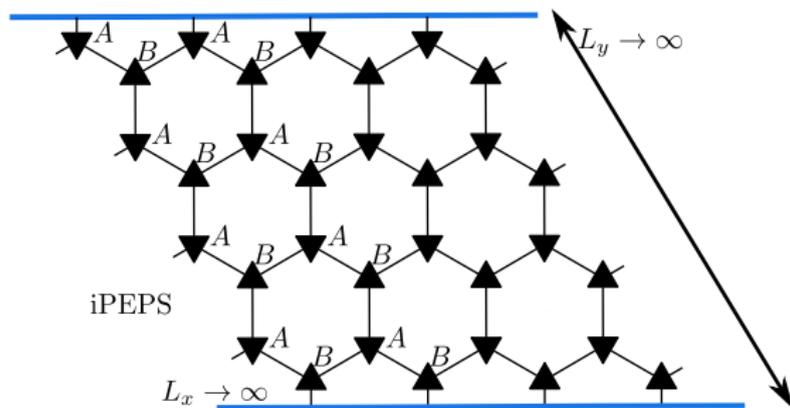
Outlook

- More complicated models
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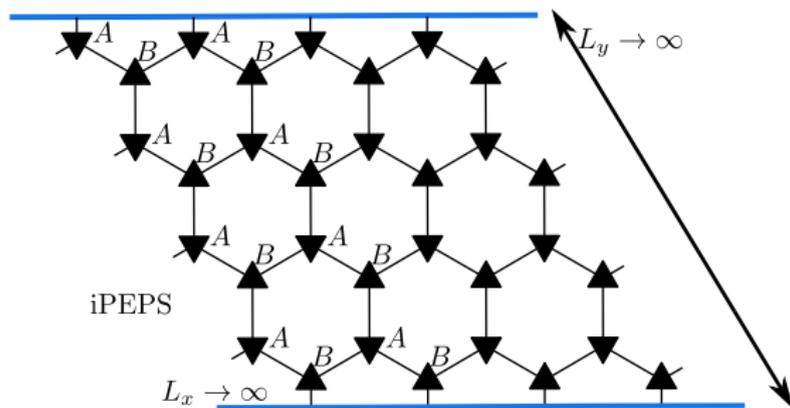
Outlook

- More complicated models
- Infinite horizon
- Continuous variables
- Planning with TN



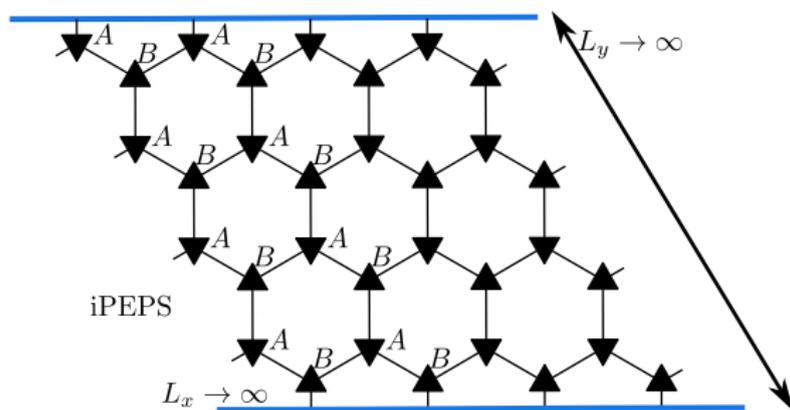


- Natural generalization of MPS to 2D

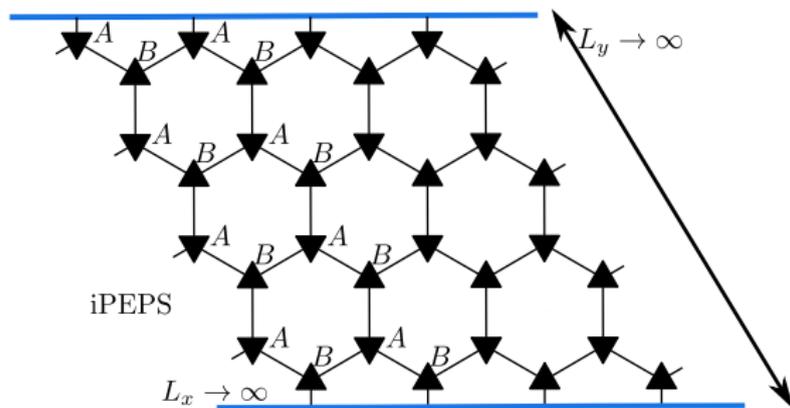


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- Allows simulations in the thermodynamic limit

PEPS



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Gapped \mathbb{Z}_2 vs gapless $U(1)$ SL in $S=1/2$ Kagome AF? H.J.Liao et al. PRL 118 (2017)

Contracting PEPS: Corner Transfer Matrix⁴

Energy gradient

Energy gradient

- Numerical gradients:

Energy gradient

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- Finite difference: $\frac{\partial F}{\partial A_i} = \frac{F(A+\delta \mathbf{a}_i) - F(A)}{\delta} + \mathcal{O}(\delta)$

expensive, erroneous

- Summation of terms with hole fixed and different Hamiltonian locations:

approximate, expensive for 'larger' Hamiltonians

P. Corboz, PRB 94, 035133 (2016),

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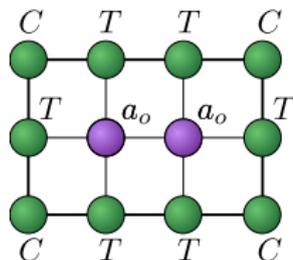
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- Analytical gradients: Automatic/Algorithmic differentiation
memory expensive, can be problematic if treated as black box
H-J. Liao, J-G. Liu, L. Wang, and T, Xiang, PRX 9, 031041 (2019)
J. Hasik, D. Poilblanc, F. Becca, SciPost Phys. 10, 012 (2021)

Energy gradient

Energy calculated approximately with CTM:

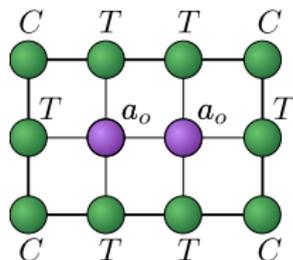
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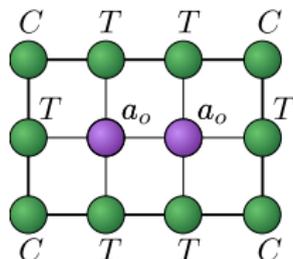


With $(C_k, T_k) \equiv x_k = f(x_{k-1}, A)$

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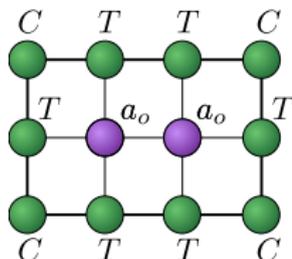
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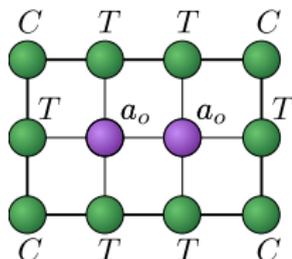
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Problems:

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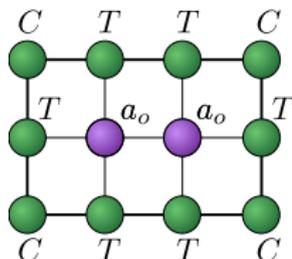
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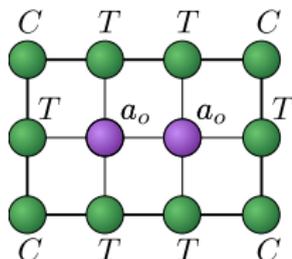
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- 2 gradient of EIG (SVD) poorly conditioned in case of degenerate spectra

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- 2 gradient of EIG (SVD) poorly conditioned in case of degenerate spectra
- 3 **currently only approximate!**

Problem: Current derivative of EIG(SVD) is only approximate

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$$M = PCP^\dagger$$

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$$M = PCP^\dagger + \underline{P_\perp C_\perp P_\perp^\dagger}$$

With $PP^\dagger + P_\perp P_\perp^\dagger = \mathbb{I}$, leading to Sylvester equation for dP :

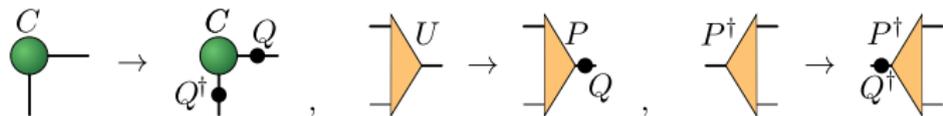
$$(\mathbb{I} - PP^\dagger)dMP = dPC - \underline{(\mathbb{I} - PP^\dagger)MdP}$$

Problem: divergencies in the gradient of EIG(SVD)

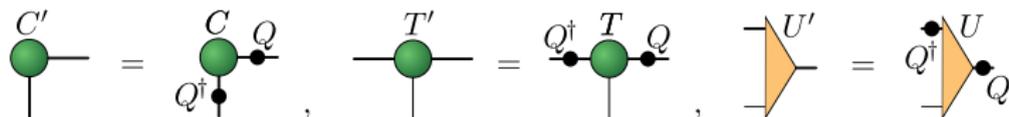
Problem: divergencies in the gradient of EIG(SVD)

Solution: Q-deformed CTM with $Q = \mathbb{I}$

(A) Q-deformation step



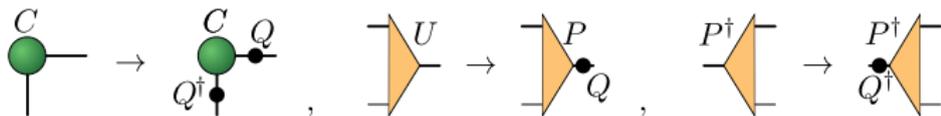
(B) Gauge transformation



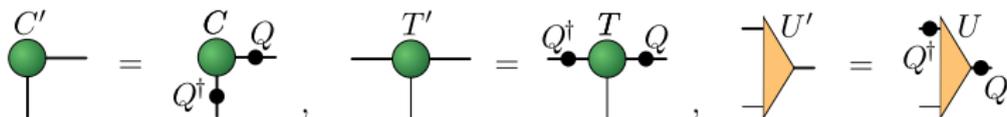
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regular CTM:

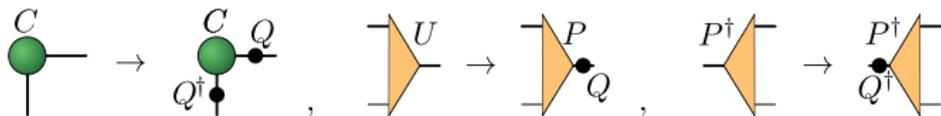
$$dC = \mathbb{I} \circ (P^\dagger dMP)$$

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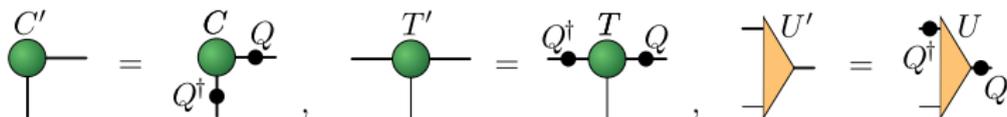
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Q-deformed CTM:

$$\begin{aligned} dC &= P^\dagger dMP \\ P^\dagger dP &= 0 \end{aligned}$$

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Hamiltonian: $H = J_1 \sum_{i,j \in NN, \alpha} f(\alpha) S_i^\alpha S_j^\alpha + J_2 \sum_{i,j \in NNN} \vec{S}_i \cdot \vec{S}_j$

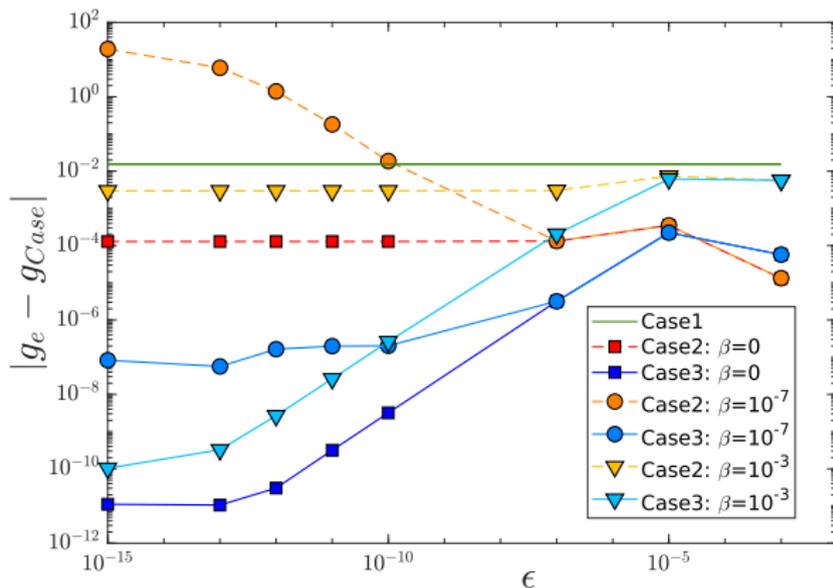
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$$F_{ij} \rightarrow \frac{c_j - c_i}{(c_j - c_i)^2 + \epsilon}$$

- our gradient g_e
- Case 1: $dP = 0$
- Case 2: current AD
- Case 3: using Sylvester equation for dP

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- reduces workcost
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- allows for more efficient algorithms
- may allow to reach higher bond dimensions D, χ and hence higher correlation lengths ξ , tackle challenging problems with bigger accuracy

Thank You